

Changes in Pitlab FPV System version 2.71

Autopilot

- Support for new board 1.3
- Option for differential throttle for twin motor airplanes. Detailed description available in document: **Differential throttle 2.71.pdf**

OSD

- Added status page for Pitlab autopilot, with status of all on-board and external sensors.
- Fixed bug in imperial date/time display (for Pixhawk/mavlink FC only)
- Increased change speed (stick reaction) in HOLD mode for altitude and course
- New menu option for differential throttle configuration in autopilot->Auto flight->Throttle mode submenu

Ground station

- Telemetry input in mavlink format, allows to work with any flight controller/FPV system providing telemetry output on ground. In this configuration GS offers all functionalities like diversity video input, tracking antenna, SD log, telemetry display and alarms.